



**MOTOROLA**  
Semiconductor Products Inc.

**AN-808**  
Application Note

ADVANCED SEMICONDUCTOR PRODUCTS, LTD.  
P.O. Box 2944, Johannesburg 2000  
3rd Floor, Vogas House  
123 Pritchard Street/Corner Mool Street  
Johannesburg  
Tel. No. DD-2856

# INTERFACING M6800 PERIPHERAL DEVICES TO THE MC68000 ASYNCHRONOUSLY

Prepared by:  
Arnold J. Morales  
Microprocessor Applications Engineer  
Austin, Texas

This application note describes a technique for interfacing M6800 peripheral devices to a MC68000 microprocessor using a four-chip TTL circuit. Any M6800 peripheral is easily interfaced to the MC68000 using the M6800 peripheral control interface (E, VMA, VPA) that is designed into the MC68000. However, when using this interface, the peripheral must be driven by the MC68000 enable (E) signal. The frequency of this clock is one-tenth of the MC68000 clock frequency with a 60/40 (6 clocks high, 4 clocks low) duty cycle. Certain applications may require a clock frequency other than the one-tenth sample that is readily available. An application using a MC68B54 Advanced Data Link Controller (ADLC) at a high data transfer rate could require an E clock frequency of up to two megahertz because the data transfer rate of the ADLC depends on the transmit and receive clocks which are limited by the E clock frequency.

## TIMING CONSIDERATIONS

Typical read and write timing for the MC68000 is shown in Figure 1. The relationship between the MC68000 timing and the access timing for the interface circuit given in this application is shown in Figure 2. The best case timing has data strobe occurring with the minimum setup time to allow peripheral selection on the next falling edge of the E clock. In the worst case timing, the data strobe did not occur in time to allow peripheral selection on the next falling edge of E. Therefore, a full E cycle has to occur and then the peripheral selection is done on the falling edge of that full cycle. The resulting cycle times for these best and worst cases and a comparison between asynchronous and synchronous interfacing is summarized in Table 1.

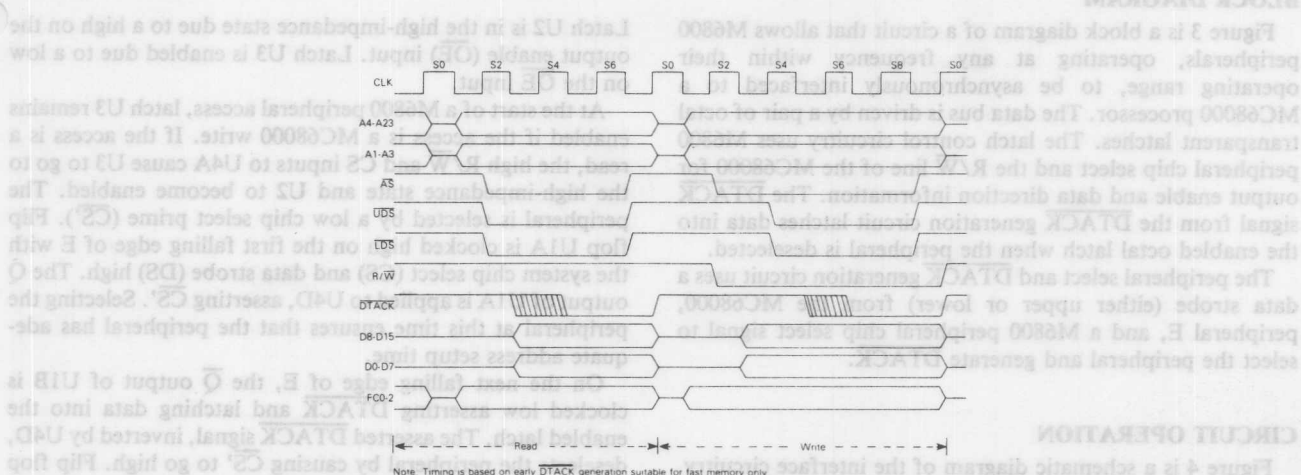


Figure 1. MC68000 Read and Write Cycle Timing Diagram

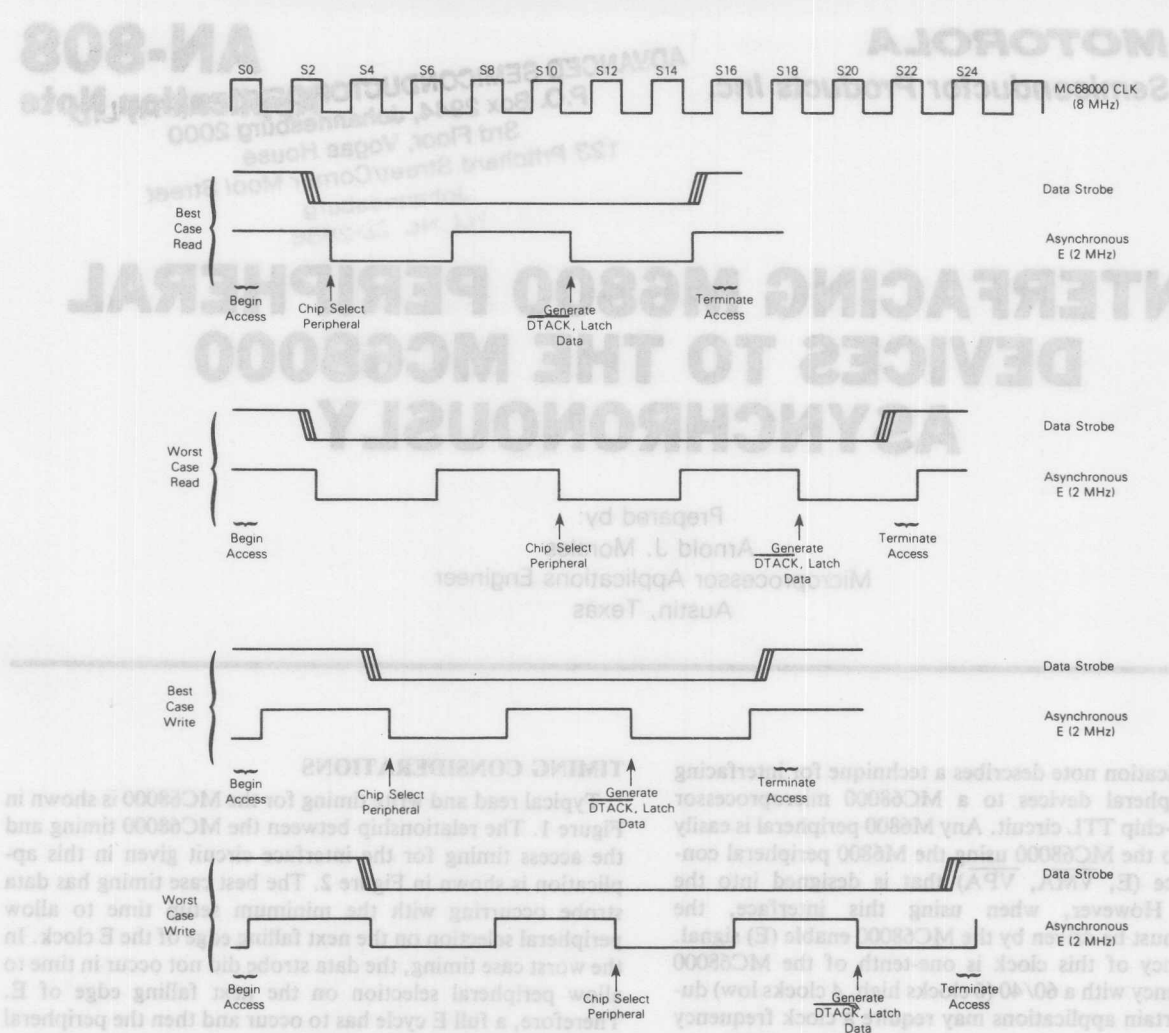


Figure 2. Asynchronous Interface Access Timing Diagrams

## BLOCK DIAGRAM

Figure 3 is a block diagram of a circuit that allows M6800 peripherals, operating at any frequency within their operating range, to be asynchronously interfaced to a MC68000 processor. The data bus is driven by a pair of octal transparent latches. The latch control circuitry uses M6800 peripheral chip select and the R/ $\bar{W}$  line of the MC68000 for output enable and data direction information. The  $\overline{DTACK}$  signal from the  $\overline{DTACK}$  generation circuit latches data into the enabled octal latch when the peripheral is deselected.

The peripheral select and  $\overline{DTACK}$  generation circuit uses a data strobe (either upper or lower) from the MC68000, peripheral E, and a M6800 peripheral chip select signal to select the peripheral and generate  $\overline{DTACK}$ .

## CIRCUIT OPERATION

Figure 4 is a schematic diagram of the interface circuitry. Refer to this diagram during the following discussion. Initially flip flops U1A and U1B are cleared causing a high  $\overline{DTACK}$  output setting U2 and U3 to a transparent mode.

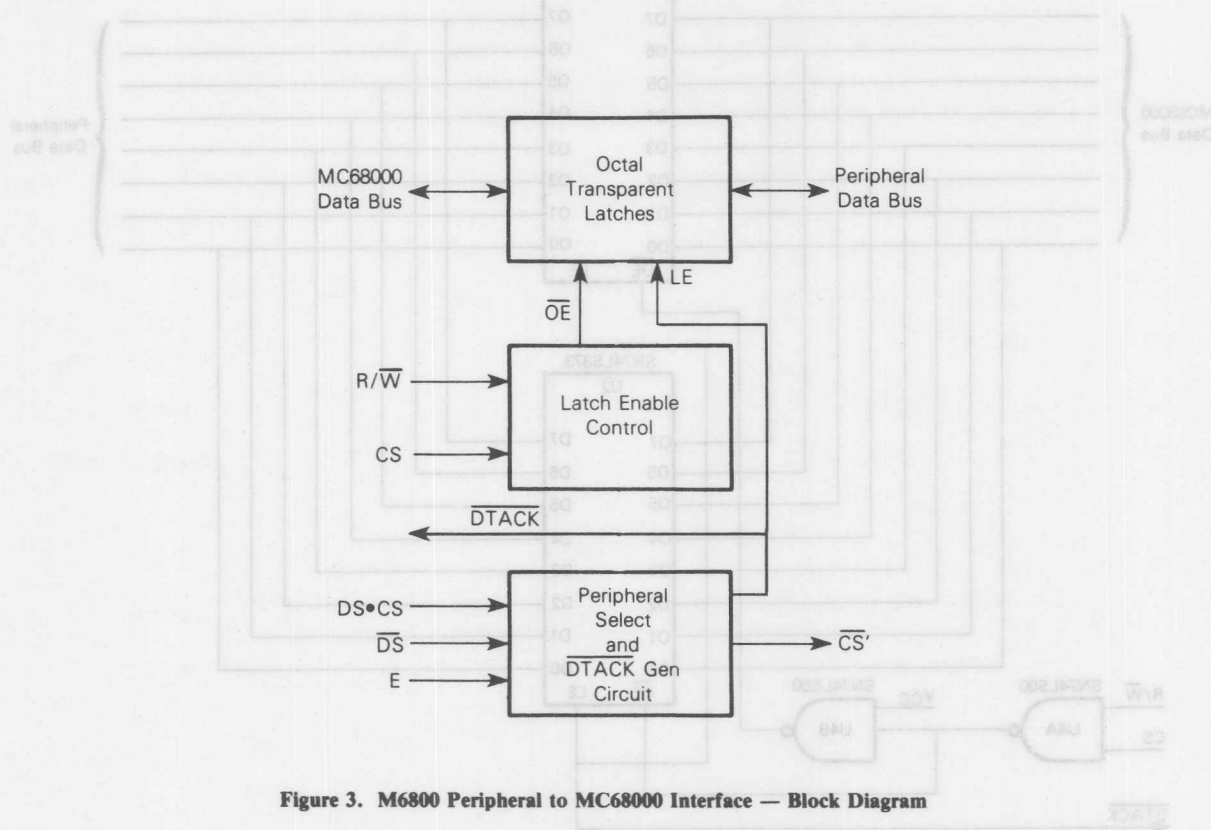
Latch U2 is in the high-impedance state due to a high on the output enable ( $\overline{OE}$ ) input. Latch U3 is enabled due to a low on the  $\overline{OE}$  input.

At the start of a M6800 peripheral access, latch U3 remains enabled if the access is a MC68000 write. If the access is a read, the high R/ $\bar{W}$  and CS inputs to U4A cause U3 to go to the high-impedance state and U2 to become enabled. The peripheral is selected by a low chip select prime ( $\overline{CS'}$ ). Flip flop U1A is clocked high on the first falling edge of E with the system chip select (CS) and data strobe (DS) high. The Q output of U1A is applied to U4D, asserting  $\overline{CS'}$ . Selecting the peripheral at this time ensures that the peripheral has adequate address setup time.

On the next falling edge of E, the  $\bar{Q}$  output of U1B is clocked low asserting  $\overline{DTACK}$  and latching data into the enabled latch. The asserted  $\overline{DTACK}$  signal, inverted by U4D, deselects the peripheral by causing  $\overline{CS'}$  to go high. Flip flop U1 is cleared by DS going low when the access terminates. Clearing U1 also initializes the interface circuitry for the next access.

**Table 1. Synchronous and Asynchronous Interface Access Time**

	Read Access Times (MC68000 Cycles)		Write Access Times (MC68000 Cycles)	
	Best Case	Worst Case	Best Case	Worst Case
Synchronous	9	18	9	18
Asynchronous	8	11	9	12



**Figure 3. M6800 Peripheral to MC68000 Interface — Block Diagram**

### SAMPLE CIRCUIT

An example of this interface circuitry is given in the following paragraphs. This example illustrates how the MC68000 can be interfaced to both a MC6854 Advanced Data Link Controller (ADLC) and a MC6840 Programmable Timer Module (PTM) at the same time. The circuit shown in Figure 5 uses the two megahertz "B" version parts connected to a MC68000 driven at eight megahertz.

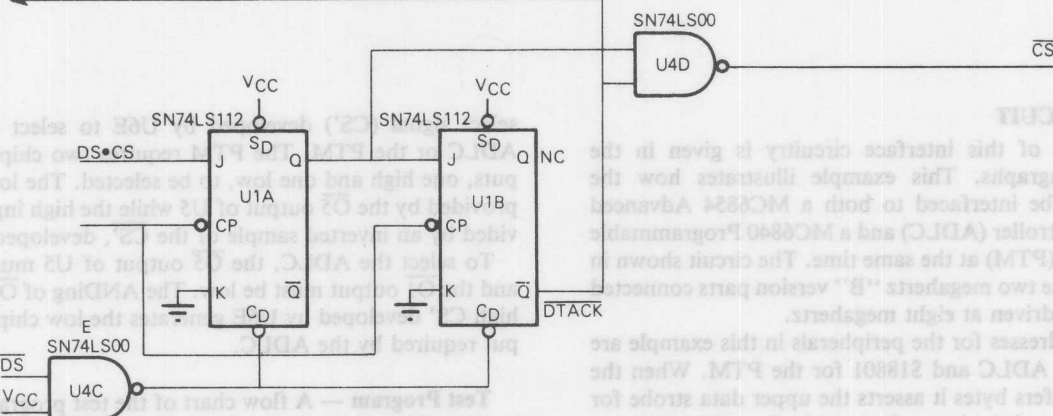
The base addresses for the peripherals in this example are \$18001 for the ADLC and \$18801 for the PTM. When the MC68000 transfers bytes it asserts the upper data strobe for even addresses and the lower data strobe for odd addresses. The circuit in this example uses the lower data strobe; therefore only odd MC68000 addresses are used. A memory map of the example system is given in Figure 6.

**Device Selection** — A SN74LS138 1-of-8 decoder (U5) used as an address decoder is used in conjunction with a chip

select signal ( $\overline{CS'}$ ) developed by U6E to select either the ADLC or the PTM. The PTM requires two chip select inputs, one high and one low, to be selected. The low input is provided by the  $\overline{O5}$  output of U5 while the high input is provided by an inverted sample of the  $\overline{CS'}$ , developed by U6E.

To select the ADLC, the  $\overline{O5}$  output of U5 must be high and the  $\overline{O1}$  output must be low. The ANDing of  $\overline{O5}$  with the high  $\overline{CS'}$  developed by U6E generates the low chip select input required by the ADLC.

**Test Program** — A flow chart of the test program is given in Figure 7 and a listing is provided in Figure 8. Refer to these figures during the following discussions. The first five lines of code initiate operation of timer 3 in the PTM in the continuous mode, resulting in a square wave at the output of timer 3, pin 6. The remaining lines of code are for testing the ADLC. The test program is based on the loopback test program given in Motorola publication MC6854UM (AD).



4





The ADLC transmitter and receiver clock inputs (TxC, RxC), are tied together and provided with a clock frequency determined by the desired data transfer rate. The transmitter output (TxD) is tied to the receiver input (RxID) to allow both the transmitter and receiver to be tested at the same time. The test consists of initializing the ADLC, transmitting a series of data bytes, and then storing the data received in a memory buffer based at address labeled RECBUF.

The byte to be transmitted, labeled DATA, is located at address \$3000. This address is entered into MC68000 address register A1, which will be used as the data pointer for data to be transmitted. The program transmits the same data byte 128 times, a count established by the initial value in MC68000 data register D0. The program can be easily modified to transmit a block of characters based at address \$3000 by changing the initial value in data register D0, and postin-

crementing address register A1 after each character is transmitted (line 72).

The main program is a looping, polling sequence. First, the receiver is checked for the presence of a received character by testing the receiver data available (RDA) flag in the ADLC. If a character is present, it is stored in the received data buffer. The transmitter data register available (TDRA) is then checked to determine whether the transmitter is ready for another byte of data. If the transmitter is ready, another data byte is transmitted. The program then loops back to check the receiver again.

Before each character is transmitted, MC68000 data register D0 is decremented and tested. Termination of the program is initiated when the correct number of characters have been transmitted.

Figure 2. MC68000/MC68014 Circuit Example

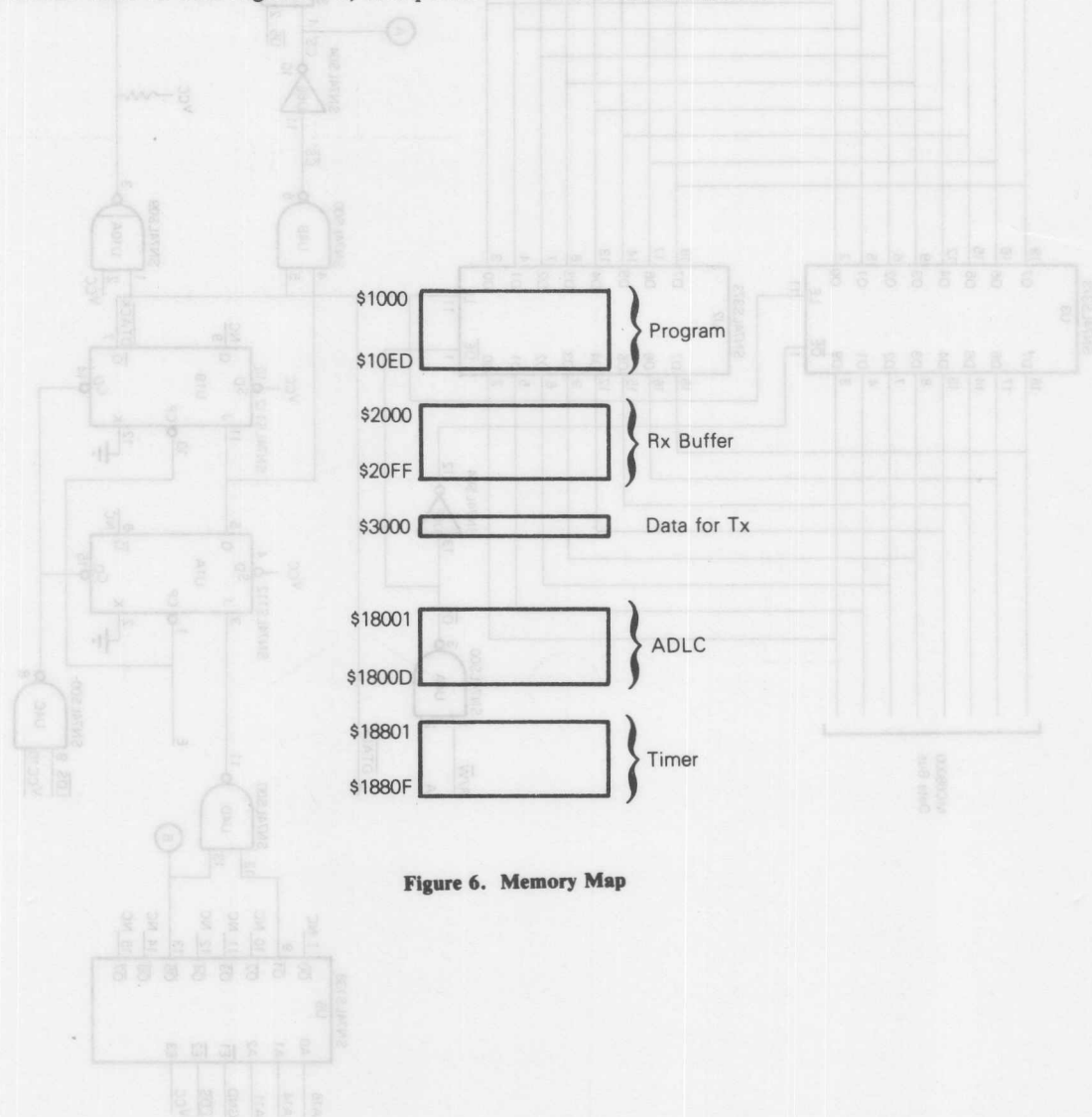


Figure 6. Memory Map

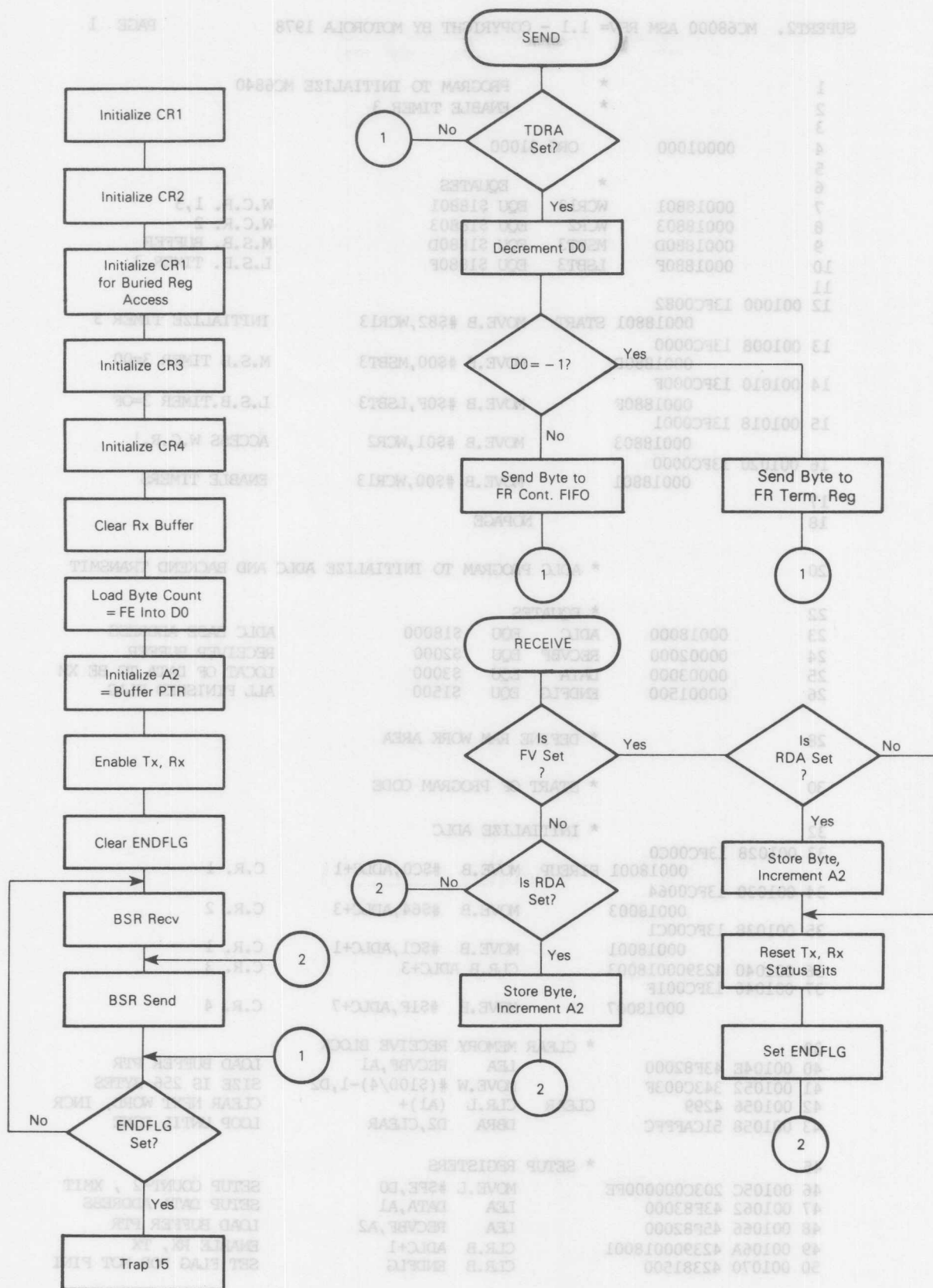


Figure 7. Program Flowchart

```

1          *      PROGRAM TO INITIALIZE MC6840
2          *      ENABLE TIMER 3
3
4          00001000      ORG $1000
5
6          *      EQUATES
7          00018801      WCR13      EQU $18801      W.C.R. 1,3
8          00018803      WCR2       EQU $18803      W.C.R. 2
9          0001880D      MSBT3      EQU $1880D      M.S.B. BUFFER
10         0001880F      LSBT3      EQU $1880F      L.S.B. TIMER 3
11
12 001000 13FC0082      00018801 START      MOVE.B #$82,WCR13      INITIALIZE TIMER 3
13 001008 13FC0000      0001880D      MOVE.B #$00,MSBT3      M.S.B TIMER 3=00
14 001010 13FC000F      0001880F      MOVE.B #$0F,LSBT3      L.S.B.TIMER 3=0F
15 001018 13FC0001      00018803      MOVE.B #$01,WCR2      ACCESS W.C.R.1
16 001020 13FC0000      00018801      MOVE.B #$00,WCR13      ENABLE TIMERS
17
18          NOPAGE
19
20          * ADLC PROGRAM TO INITIALIZE ADLC AND BACKEND TRANSMIT
21
22          * EQUATES
23          00018000      ADLC      EQU $18000      ADLC BASE ADDRESS
24          00002000      RECVBF    EQU $2000      RECEIVER BUFFER
25          00003000      DATA     EQU $3000      LOCAT OF DATA TO BE XM
26          00001500      ENDFLG    EQU $1500      ALL FINISHED FLAG
27
28          * DEFINE RAM WORK AREA
29
30          * START OF PROGRAM CODE
31
32          * INITIALIZE ADLC
33 001028 13FC00C0      00018001 FIREUP      MOVE.B #$C0,ADLC+1      C.R. 1
34 001030 13FC0064      00018003      MOVE.B #$64,ADLC+3      C.R. 2
35 001038 13FC00C1      00018001      MOVE.B #$C1,ADLC+1      C.R. 1
36 001040 423900018003  00018003      CLR.B ADLC+3      C.R. 3
37 001046 13FC001F      00018007      MOVE.B #$1F,ADLC+7      C.R. 4
38
39          * CLEAR MEMORY RECEIVE BLOCK
40 00104E 43F82000      LEA      RECVBF,A1      LOAD BUFFER PTR
41 001052 343C003F      MOVE.W #($100/4)-1,D2      SIZE IS 256 BYTES
42 001056 4299          CLEAR      CLR.L (A1)+      CLEAR NEXT WORD, INCR
43 001058 51CAFFFC      DBRA     D2,CLEAR      LOOP UNTIL DONE
44
45          * SETUP REGISTERS
46 00105C 203C000000FE      MOVE.L #$FE,D0      SETUP COUNT-2 , XMIT
47 001062 43F83000      LEA      DATA,A1      SETUP DATA ADDRESS
48 001066 45F82000      LEA      RECVBF,A2      LOAD BUFFER PTR
49 00106A 423900018001      CLR.B ADLC+1      ENABLE RX, TX
50 001070 42381500      CLR.B ENDFLG      SET FLAG FOR NOT FINI

```

Figure 8. Program Listing



```

52                                     * PROCESS TRANSMIT AND RECEIVE TASK TILL DONE
53 001074 61000038 PROCES BSR RECV ATTEMPT RECEIVE
54 001078 6100000C BSR SEND ATTEMPT TO SEND
55 00107C 4A381500 TST.B ENDFLG FINISHED?
56 001080 67F2 BEQ PROCES LOOP IF NOT FINISHED
57 001082 4E4F TRAP 15 BREAKPOINT WHEN FINIS
58 001084 0000 DC.W #0 BREAKPOINT CODE

60                                     * ATTEMPT TO TRANSMIT A CHARACTER
61 001086 08390006
    00018001 SEND BTST.B #06,ADLC+1 TDRA SET? XMIT READY?
62 00108E 67000014 BEQ RETURN
63 001092 0C40FFFF CMP #-1,D0 ? LAST BYTE SENT?
64 001096 6700000C BEQ RETURN YES IGNORE SENDING MO
65 00109A 51C8000A DBRA D0,MORE COUNT DOWN, BRANCH NO
66                                     * PROCESS LAST BYTE BY TERMINATING TRANSMISSION
67 00109E 13D100018007 MOVE.B (A1),ADLC+7 LAST BYTE INTO FRAME
68 0010A4 4E75 RETURN RTS RETURN TO MAINLINE
69                                     * PROCESS NEXT BYTE TO TRANSMIT (NOT THE LAST)
70 0010A6 13D100018005 MORE MOVE.B (A1),ADLC+5 SEND NEXT BYTE TO FRA
71 0010AC 4E75 RTS RETURN TO CALLER

73                                     * ATTEMPT TO RECEIVE A CHARACTER
74 0010AE 08390001
    00018003 RECV BTST.B #1,ADLC+3 ? FRAME RECEIVED
75 0010B6 66000008 BNE GOTFRM BRANCH IF SO
76 0010BA 61000016 BSR TRYINP ATTEMPT INPUT OF NEXT
77 0010BE 4E75 RTS RETURN TO MAINLINE
78                                     * END OF FRAME PROCESSING
79 0010C0 61000010 GOTFRM BSR TRYINP INSURE LAST BYTE PROC
80 0010C4 13FC0064
    00018003 MOVE.B #$64,ADLC+3 CLEAR TX,RX STATUS
81 0010CC 52381500 ADD.B #1,ENDFLG FLAG RECEIVER DONE
82 0010D0 4E75 RTS RETURN TO MAINLINE

84                                     * PROCESS INPUT BYTE IF ANY
85 0010D2 08390000
    00018001 TRYINP BTST.B #0,ADLC+1 ? INPUT BYTE READY, T
86 0010DA 67C8 BEQ RETURN RETURN IF NO BYTE
87 0010DC 14F900018005 MOVE.B ADLC+5,(A2)+ STORE BYTE
88 0010E2 4E75 RTS RETURN

90                                     END
91
92                                     *©

```

\*\*\*\*\* TOTAL ERRORS 0-- 0

#### SYMBOL TABLE

ADLC	018000 CLEAR	001056 DATA	003000 ENDFLG	001500
FIREUP	001028 GOTFRM	0010C0 LBSB3	01880F MORE	0010A6
MSBT3	01880D PROCES	001074 RECV	0010AE RECVBF	002000
RETURN	0010A4 SEND	001086 START	001000 TRYINP	0010D2
WCR13	018801 WCR2	018803		

Motorola reserves the right to make changes to any products herein to improve reliability, function or design. Motorola does not assume any liability arising out of the application or use of any product or circuit described herein, neither does it convey any license under its patent rights nor the rights of others.

Figure 8. Program Listing (Concluded)

MOTOROLA Semiconductor Products Inc.



